Recent Advancements in Noncommutative Gröbner Basis Software



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based on joint work with Maximilian Heisinger





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Noncom. polynomial
$$c_1 \cdot w_1 + \dots + c_d \cdot w_d \in \mathsf{K}\langle x_1, \dots, x_n \rangle$$
 words over x_1, \dots, x_n

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$$xyyx + 2xy - yx - 2 \in \mathbb{Q}(x,y)$$

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Multiplication = concatenation of words
$$(xy-1) \cdot (yx+2) = xyyx + 2xy - yx - 2$$

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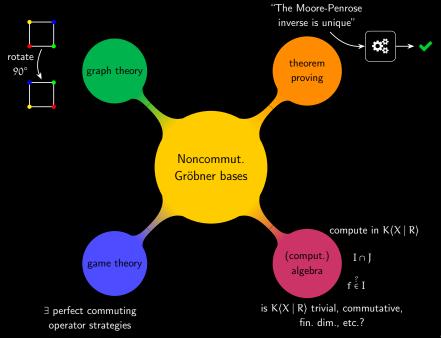
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Noncomm. GB theory = comm. GB theory - finiteness

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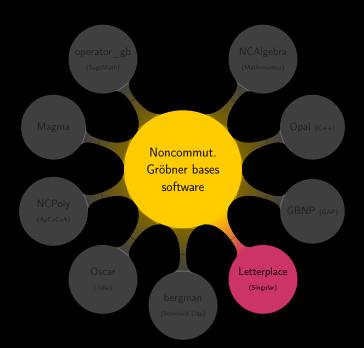


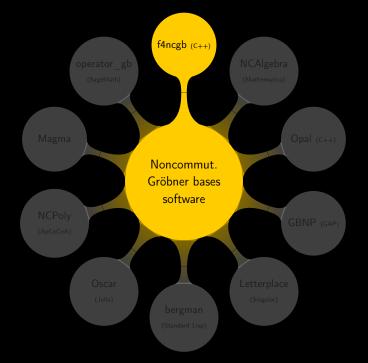




Example	Letterplace	1 core	f4ncgb 4 cores	16 cores
4nilp5s-10	1282	150	79	63
braid3-16	18 953	105	34	18
braidXY-12	1847	62	52	52
holt_G3562h-17	>43 200	25 021	12 671	6824
lascala_neuh-13	171	9	5	
lp1-15	24 166	266	179	155
lv2d10-100	>43 200	48	27	47
malle_G12h-100	4142	89	74	73

(Timings in sec)





f4ncgb

Open-source C++ library that ports commutative advancements to the noncommutative setting.

- Gröbner basis computation in $\mathbb{Q}\langle X \rangle$ and $\mathbb{Z}_p\langle X \rangle$ for prime $p < 2^{31}$
- Several orders of magnitude faster than current state of the art
- Proof logging via cofactor representations
- Soon part of





Data structures

- Monomials are unique and referenced
- Coefficients are shared
- Prefix tree for divisions

Algorithms

- Noncomm. F4 algorithm
- Sparse linear algebra (multi-modular, parallelized, probabilistic)
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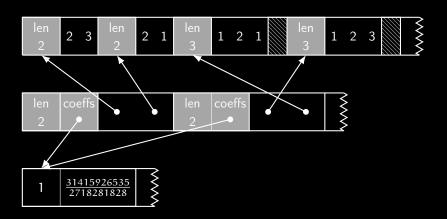
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Monomials & Polynomials

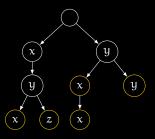
Represent vars by index according to mon. order: $x_1 < x_2 < \cdots < x_n$ $\downarrow \qquad \downarrow \qquad \downarrow$



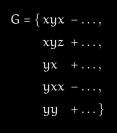
Observation: divisor candidates are always the same (lm's of the GB) Exploit this information → keep prefix tree of all leading monomials

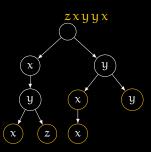
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$$G = \{ xyx - \dots, \\ xyz + \dots, \\ yx + \dots, \\ yxx - \dots, \\ yy + \dots \}$$

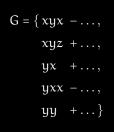


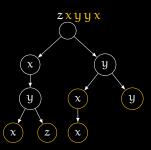
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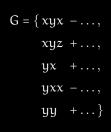


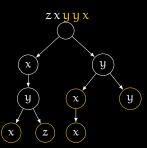
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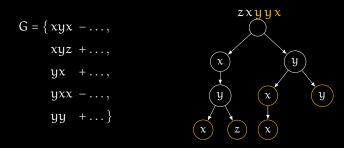


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Given input f_1, \ldots, f_r , write each $g \in GB$ as

$$g = \sum_{j} p_{j} \cdot f_{j} \cdot q_{j}$$
 "cofactor representation"

with $p_j, q_j \in K\langle X \rangle$.

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$$\begin{pmatrix} - & \mathfrak{p}_1 & - \\ & \vdots & \\ - & \mathfrak{p}_k & - \end{pmatrix} \longrightarrow \mathsf{RRef}$$

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$$T \cdot \begin{pmatrix} - & p_1 & - \\ & \vdots & \\ - & p_k & - \end{pmatrix} = RRef$$

The rows of T give cofactor representations of g_i in terms of f_1, \ldots, f_r and g_1, \ldots, g_{i-1} .

Substitution yields representations w.r.t. f_1, \ldots, f_r (\triangle exp. blowup!)

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